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New Challenges in Safeguards

Surveillance, containment and NDA measurements »» »» "Continuity of Knowledge" (CoK) between 2 inspections

Facilities are getting more and more complexNumber and complexity of facilities are increasingNumber of inspections days should be reduced..



New Challenges in Safeguards

⇒IAEA SG needs to address these 2 challenges: continuously improve the effectiveness..

New techniques need to be:

- evaluated,
- presented to the operators
- implemented.

Laser based application present wide variety of possibilities:

- Some are already used
- Some are future but very promising test results



- 3 Dimensional Laser Range Finder (3DLR)
- Outdoor Verification system (OVS)
- Combined 3DLR with radiation map
- Laser Item Identification System for UF6 Cylinders,
- Laser Mapping for fuel packaging,
- Laser Surface Authentication for metal seals verification
- Light Detection and Ranging (LIDAR)
- Tunable Diode Laser Spectroscopy (TDLS)



Design Information and Verification (DIV):

- in vast and complexes facilities,
- with infrequent access possibility,
- loss of knowledge along the years,
- rotation of inspectors,
- huge amount of data...

Facilities are getting more and more complex
Improving DIV activities
required a "tool".



The Tool & the Need:

Automate the capture of the design:
O To increase the accuracy of the Design Information original verification,
O To increase DIV effectiveness.

Automate the verification of the design:

- o To reduce the data acquisition time at facility,
- o To reduce the data processing effort.



IAEA Inspector using the 3DLR.

Courtesy of the EC/ IPSC/ JRC Ispra, IAEA SGTSR.



Dedicated tool:



IAEA Inspector setting up the 3DLR acquisition.

Courtesy of the EC/ IPSC/ JRC Ispra, IAEA SGTSR.

-based on a 3 dimensional laser range finder,

- with safeguard adapted software (developed under the European Support Program to the IAEA).





The **3DLR** is used in Rokkasho reprocessing plant since May 2003 first demonstration.



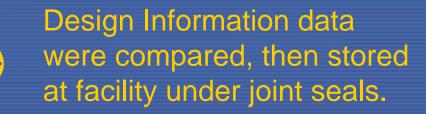
IAEA Inspector performing a 3DLR scan. IAEA SG- JNFL.

Cells were scanned during construction and again just before closing,



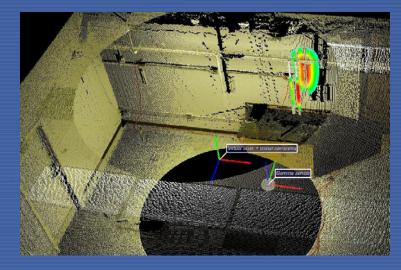


IAEA Inspector performing a 3DLR verification. Courtesy of the EC/ IPSC/ JRC Ispra, IAEA SGTSR.



In 2007, what is new ?

Combined 3DLR with radiation map



Courtesy of the EC/ IPSC/ JRC Ispra, LLNL and ORNL. -AVI animation can be presented after the presentation-

Merging 3D models with:

Gamma ray map,Infra red map...



In 2007, what is new?

Outdoor 3DLR ?

Perform eventual outside facilities building DIV.

Use the same concept:

- 3-Dimensional laser range finder
- with broader range,
- coupled to digital camera
- linked to a positioning system \rightarrow enabling scanning in movement



Outdoor 3DLR

The 3D-laser scanner

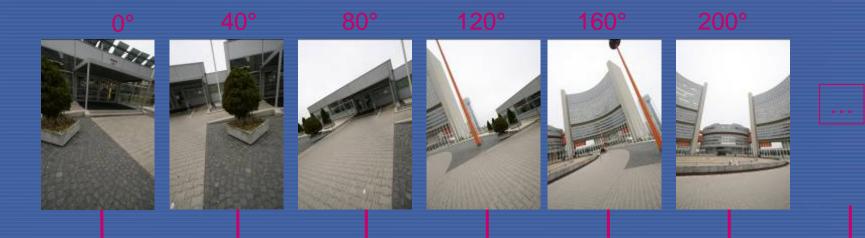
image of the reflection of the object function of the light intensity



Entrance from the Vienna International Center ; IAEA head quarters Scan courtesy of the EC/ IPSC/ JRC Ispra



Outdoor 3DLR



Entrance from the Vienna International Center ; IAEA head quarters Picture courtesy of the EC/ IPSC/ JRC Ispra

The digital camera mounted on the top of the laser scanner captures 7 pictures at each scanning point,

During the data processing overlaid on top of the 3D data.



Outdoor 3DLR

3D data

Set of pictures



Construction of a 3D model :

virtual but almost real !





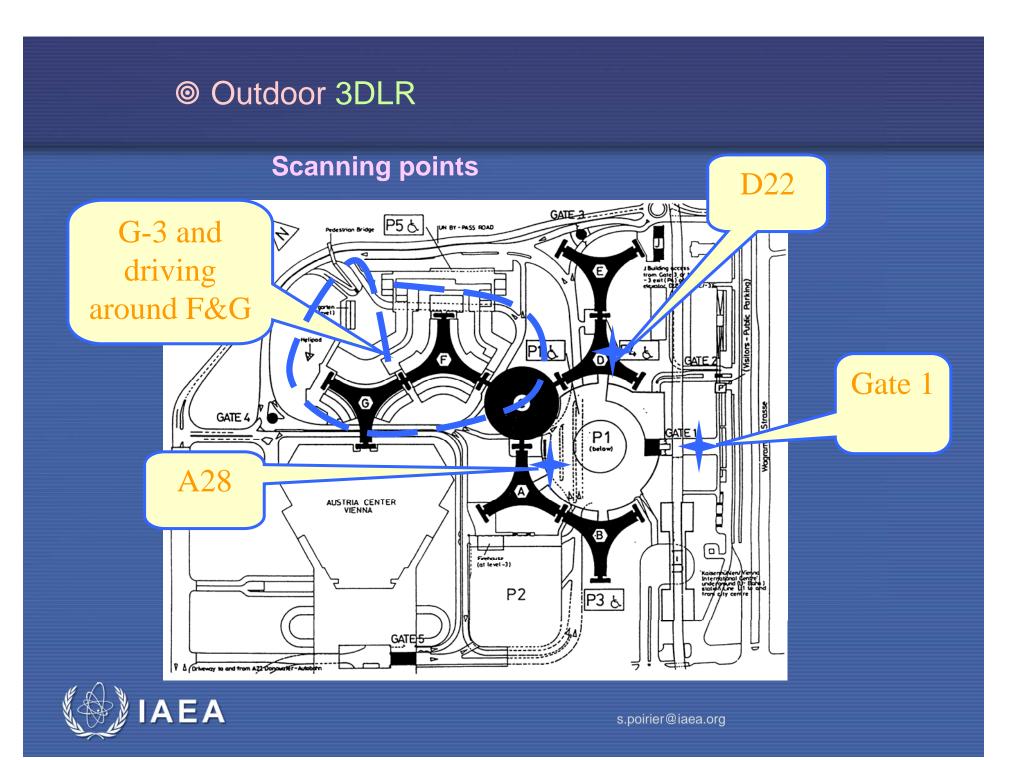
Outdoor 3DLR demonstration: IAEA head quarters in Vienna

11 range scans 77 colour pictures,

Making of movie Can be presented After the presentation.



ΕA



Item tracking

Number of facilities is increasing
 Number of increasing days about the rest

Number of inspections days should be reduced..

Develop or improve
 new surveillance and containment techniques



Item tracking : UF6 cylinders identification:

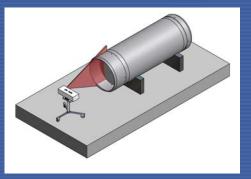
in Enrichment facilities,
monitoring the UF6 cylinders movement,
without relying on any

existing or
additional tagging.



UF6 cylinders identification:

Systematically referencing of all UF6 Cylinders:



IAEA/ SGTS/ M Lang.

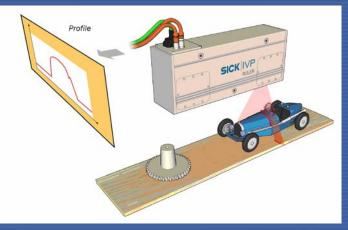
O delivered (shipping in)O declared to be used in the coming months.

Unattended scan of transported cylinders entering and exiting the process area.



UF6 cylinders identification:

The Technique:



Triangulation concept- source SICK Laser Reference Manual.

-based on a triangulation laser scanner

- with safeguard adapted software (developed under the European Support program to the IAEA).

> The Laser Item Identification System (L2IS)



UF6 cylinders identification: Laser Item Identification System (L2IS)

First application: trial in Rokkasho enrichment plant September 14th – November 9th 2007.

- UNIT 1 Records & Identifies all cylinders declared to be "used" by the operator
- UNIT 2 Verifies that all cylinders "used*" by the operator are matching the declaration list of operator's declaration.

Under Trial

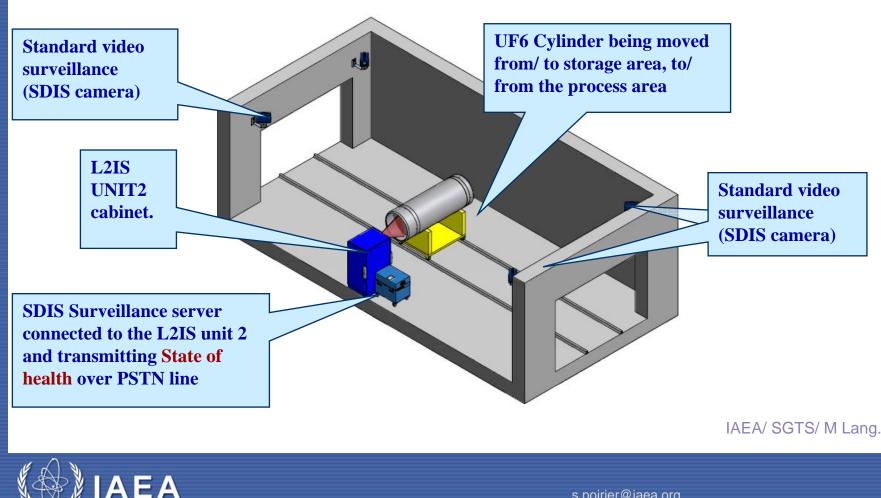


L2IS at REP-09/2007 Courtesy of the JNFL





UF6 cylinders identification: Laser Item Identification System (L2IS)



UF6 cylinders identification: Laser Item Identification System (L2IS)

Ourrent stage of the trial:

- Portable unit1 is operational,
- Installed unit 2 needs to be adapted to:
 - Cope with the distance between scanner and smaller cylinders
 - Scan cylinders without stopping the transported cylinders

Milestones:

November 2007:

March 2008:

April 2008:

data retrieval after 60 days initial trial period
→ analyse
Upgrade of unit 1 and unit 2 to cope with the facilities geometrical constraints (REP)
Second phase of aging test



Develop and implement new containment verification techniques

between fuel fabrication plant
and receiving plant
verifying the surface and welding .

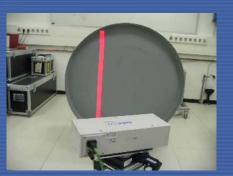
- Laser surface mapping

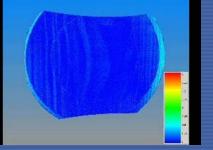


Laser surface mapping for fuel packagingOsystematically referencing all packaging

meant to be used for the fuel shipment
Part of sealing arrangement
Proof of integrity of the entire container surface incl. welds

Random verification
 o at receiving facility
 o the surface,
 o and welding





Courtesy of the EC/ IPSC/ JRC Ispra IPSC, V Sequeira.



Laser surface mapping for fuel packaging



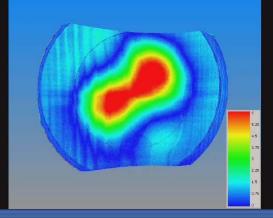




1. Tampering

2. Re-welding

3. Painting



4. Verification scan:impossible to hidethe surface deformation

Pictures Courtesy of the EC/ IPSC/ JRC Ispra IPSC, V Sequeira.



Laser surface mapping for fuel packaging

©Current stage :

- Demonstration performed September 2007 PFPF.

Milestones:

November 2007: expected report from EC/JRC Ispra.



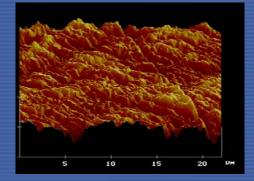
Laser based applications: Existing and Future Solutions. Improve existing containment verification techniques effectiveness

Automate the metal seals verification
Offer on site / on the spot verification

Laser Surface Authentication (LSA®):

Laser beam produces speckle light from the microscopic surface

→ 'fingerprint'



Surface Roughness at Laser Wavelength Scales - Photo Courtesy of Ingenia Technologies Limited-.



Laser Surface Authentication for Metal seal Verification:



Surface Roughness at Laser Wavelength Scales -Photo Courtesy of Ingenia Technologies Limited-.

- counterfeit resistant signature
 - low cost
- Small amount of data

©Current stage:

- initial feasibility assessment for LSA successfully completed ,
- third party design vulnerability assessment is in progress.

Milestones:

- 2008 First prototypes in IAEA HQ
- on-site and/or in-situ verification ...

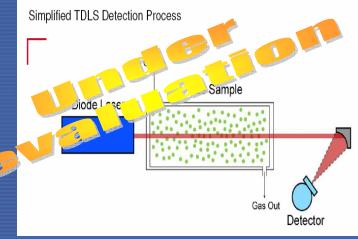


Measurement of UF6 at enrichment plants. Development of an instrument: - foreseen to determine in UF6 on-site

- expected accuracy < 1% for 235U

Tunable Diode Laser Spectroscopy (TDLS):

Diode lasers access specific regions of the mid-infrared spectrum where most gases of interest have strong absorption while common gases, such as oxygen and nitrogen, do not have strong absorption.



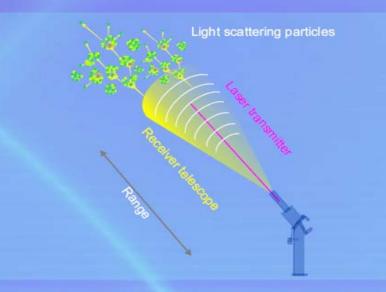


Laser based applications: **Existing and Future Solutions.** Tunable Diode Laser Spectroscopy (TDLS): Extreme sensitivity (~ ppb concentration range) quick measurements • high spectral resolution in the IR range, no special safety measure for operation, inside and outside a facility, portable TDLS system was successfully demonstrated to detect ppb concentrations of HF.



Light Detection and Ranging (LIDAR)

Detecting the presence and nature of nuclear process activities at suspected nuclear locations using light detection and ranging (LIDAR)



1 A mobile LIDAR laboratory travels to the vicinity of a suspected location. 2 A laser, tuneable to precise wavelengths, selectively stimulates specific airbome molecules that emanate as gaseous compounds from nuclear processes.



3 A light sensitive telescope scans the stimulated atmosphere, detecting the presence, or absence of the stimulated signature molecules. 4 The returned light from the atmosphere is analysed, identifying the compound type and the location of its source.

Source: RF MSSP



Conclusions

Laser based applications

- Existing : 3DLR,L2IS
- Development / Evaluation: OVS, Gamma Ray mapping, Laser surface mapping
- Future techniques: TDLS, LIDAR.

will play an increasingly role in

both the provision of appropriate verification
 and detection tools for current and future safeguards activities.



Conclusions

IAEA SG Technical Support's guidelines:

- Use of the shelves equipment
- Adapt to the technical need
- Comply to the IAEA SG requirements
- Present and install at facilities

Most of these new techniques:

- Part of the SG at enrichment plant's "toolbox" project,
- Supported by Member state support programs:
 - funding,
 - research institutes and laboratories,
 - trial hosting at facilities.





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M. McGlade, S. Poirier, H. Undem, M. Zendel, Laser Surface Authentication for Containment and Surveillance, IAEA Symposium 2006 on International Safeguards, IAEA-CN-148/123, Vienna, Austria.

• TDLS: Annual Report-WG-TDLS for IAEA SG



Technical references 3DLR

Scan duration (for standard 360° × 182° scan)

Reference scan :

- Super High Resolution 20,000 x 10,111 points 6m 44s
- High Resolution 10,000 x 5,055 points 3m 22s Average of 6scans / cell: 1 to 2 hours (access conditions)

Verification scan:

- Super High Resolution 20,000 x 10,111 points 6m 44s
- High Resolution 10,000 x 5,055 points 3m 22s
- Middle Resolution 5,000 x 2,527 points <u>1m 41s</u> (Mostly used for IAEA SG)

